The hyperspectral Mission DESIS Entering the operational Phase

<u>Rupert Müller(1)</u>, Kevin Alonso(1), Martin Bachmann(1), Kara Bruch(3), Emiliano Carmona(1), Daniele Cerra(1), Daniele Dietrich(1), Birgit Gerasch(1), Burghardt Günther(1), Heath Lester(2), Uta Heiden(1), Jack Ickes(2), Uwe Knodt(1), Harald Krawczyk(1), David Krutz(1), Ben Murphy(2), Mary Pagnutti(3), Mirco Tegler(1), Robert Ryan(3), Raquel de los Reyes(1), Thomas Säuberlich(1), Ilse Sebastian(1), Valentin Ziel(1), Ingo Walter(1)

Wissen für Morgen

1 DLR German Aerospace Center, Oberpfaffenhofen, Berlin, Cologne, Germany

2 Teledyne Brown Engineering, Huntsville, USA

3 I2R Innovative Imaging and Research Corp, Stennis Space Center, USA



Teledyne Brown Engineering (USA) and DLR have partnered to build and operate the DLR Earth Sensing Imaging Spectrometer (**DESIS**) from the Teledyne-owned Multi-User System for Earth Sensing (MUSES) Platform on the ISS

MUSES provides accommodations for two large and two small hosted payloads and provides **core services** for the instruments like

- Position via GPS (1 Hz)
- Attitude via Startracker + MIMU (10 Hz)
- Master time (acc. <150 µsec)
- **2 Gimbals** ±25° for/back; 45° backboard; 5° starboard
- Downlink 225 Gbit / day Ku band

DLR developed the hyperspectral sensor **DESIS**, which is currently the first payload

DLR established the Ground Segment and licensed the SW processors to Teledyne running in an Amazon Cloud



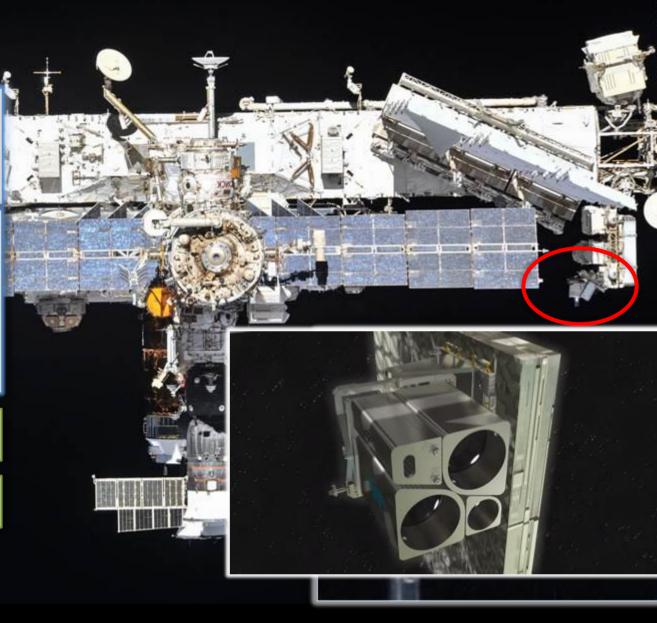
onBoard Calibration

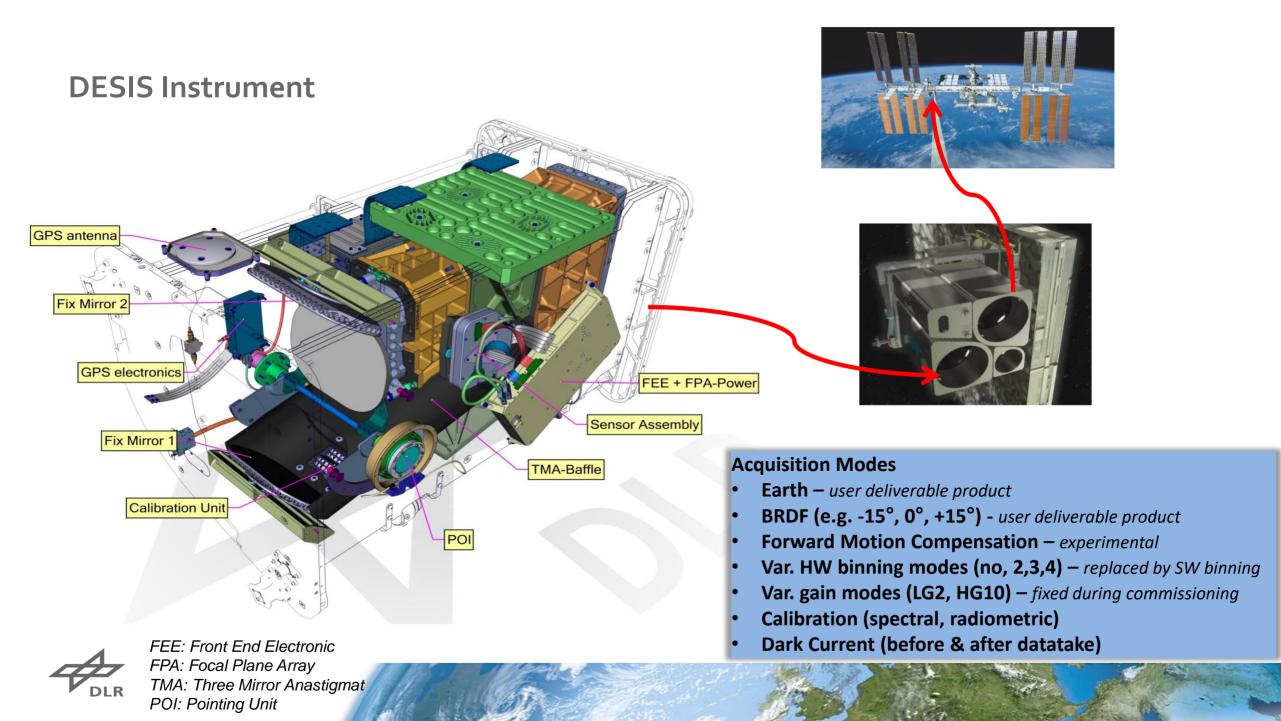


Data Archiving@DLR



Data Distribution@DLR





Mission Instrument	ISS/MUSES DESIS	EnMAP HSI (2 instruments)		
Off-nadir tilting	-45° (backboard) to +5° (starboard), -40° to +40°	-30° to +30°,		
(across-track, along-track)	(by MUSES and DESIS)	0° (by EnMAP)		
Spectral range	400 nm to 1000 nm	420 nm to 2450 nm		
Spectral Sampling (res., acc.,bands)	2.55 nm, 0.5 nm, 235	6.5 nm, 0.5 nm (VNIR),		
	118 (bin 2), 79 (bin 3), 60 (bin 4)	10.0 nm, 1.0 nm (SWIR)		
Radiometry (res., acc.)	13 bits, ~10%	14 bits, 5%		
Spatial (res., swath)	30 m, 30 km (@ 400 km)	30 m, 30 km		
SNR (signal-to-noise)	195 (w/o bin.) / 386 (4 bin.) @ 550 nm	500 @ 495 nm, 150 @ 2200 nm		
Instrument (mass)	93 kg	350 kg		
Capacity (km, storage)	2360 km per day, 225 GBit	5000 km per day, 512 GBit		
		EnMAP HSI (2 instruments)		
Target lifetime	2018-2023	2021-2026		
Satellite (mass,	455 t, 109.0×97.9×27.5 m ³	1 t, 3.1×2.0×1.7 m ³		
dimension, usage)	(multi-purpose)	(single-purpose)		
Orbit (type, local time at equator,	not Sun-synchronous, various,	Sun-synchronous, 11:00,		
inclination, height, repeat cycle)	51.6°, 320 km to 430 km,	98.0°, 653 km,		
	no repeat cycle	398 revolutions in 27 days		
Coverage	55° N to 52° S	74° N to 74° S		
Revisit frequency	3 to 5 days (average)	≤ 4 days, ≤ 27 days (±5° tilting)		

Note: FPA of DESIS is the same as for EnMAP VNIR Note: high overlap in on-ground processing

=> DESIS can be also regarded as a precursor of EnMAP

DESIS (DLR Earth Sensing Imaging Spectrometer) MUSES (Multi-User System for Earth Sensing) ISS (International Space Station)

Current Status of the imaging spectrometer DESIS on the multi-payload platform MUSES installed on the ISS



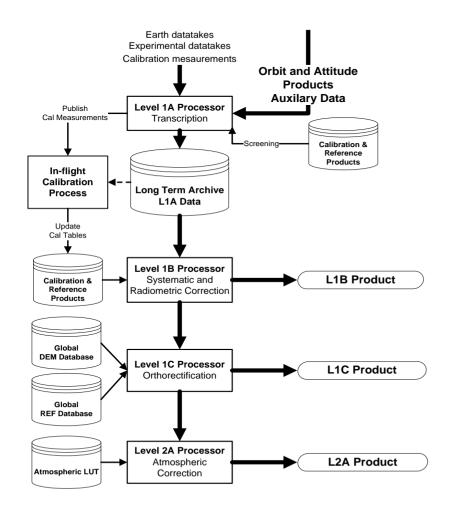


2014 / 2015 MUSES / DESIS mission starts 7. June 2017 MUSES installation on ISS 29. June 2018 DESIS launch from Cape Canaveral to ISS via SpaceX Dragon 27. - 28. August 2018 Unpacking of DESIS and installation in MUSES

- Leaving Commissioning Phase, but some remaining tasks
- Commercial Data delivery already started



Data Processing Which products are getting the user



Products:

- Level 0 (L0)
 - Raw data (Datatakes up 100 tiles 30x30 km², trajectory files, DC)

– Level 1A (L1A)

Tiled images, browse image, metadata, quality flags <= archived.

- Level 1B (L1B)*

- Top of Atmosphere (TOA) radiance (W.m-2.sr-1.µm-1)
- Systematic and radiometric correction (rolling shutter, smile, suspicious pixels,....)
- All metadata attached for further processing

– Level 1C (L1C)*

- Level 1B data ortho-rectified, re-sampled to a specified grid
- Global DEM (Aster GDEM v2), sensor model refinement using global reference image (Landsat-8 PAN with acc. 18m CE90)

– Level 2A (L2A)*

- Ground surface reflectance (i.e. after atmospheric corrections)
- With and w/o terrain correction

Processors at the Ground Segments

- Fully automated
- Run 'on-request' over archived data
- Two instances: one at Teledyne (Amazon Cloud), one at DLR. Same processing



* Delivery product

Quality Layers and Metadata

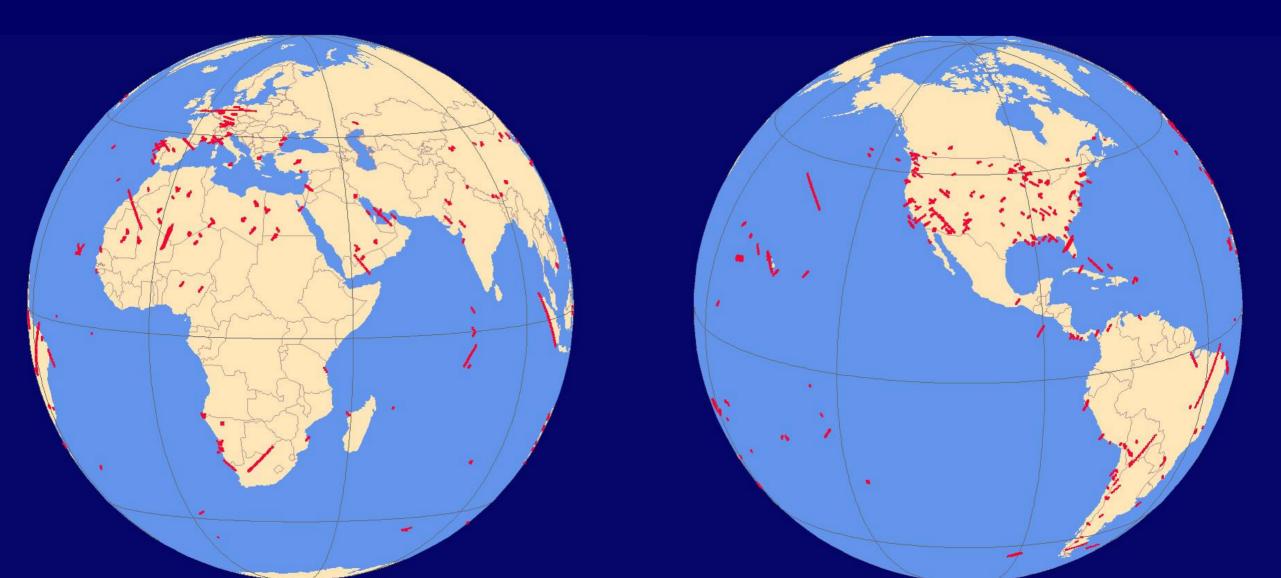
Quality Layer (Geotiff)	L1A	L1B	L1C	L2A
Dead pixels		Х	Х	Х
Suspicious pixels		Х	Х	Х
Too high radiance level		Х	Х	Х
Too low radiance level		Х	Х	Х
Shadow				Х
Clear Land				Х
Clear Water				Х
Haze over land				Х
Haze over water				Х
Cloud over land				Х
Cloud over water				Х
Aerosol optical thickness				Х
Perceptible water vapour				Х
Detector Map (Digital Number)	Х			
Detector Map (Radiance Level)	Х			

- Dead Pixels
 - generated through calibration
- Suspicious pixels
 - Generated by comparison between measured radiances and calibration
- Data Screening
 - Temperatures, Voltages, Currents, CRC, Dark Currents
- Geometric accuracy
 - Subset of matching points with reference
- Bad columns/lines (based on detector maps)
 - Generated by statistical tests
- Smile Indication
 - Based on Absorption Bands (like O2 at 760 nm)



			haze	haze	Cloud	Cloud	Aerosol optical		
Shadow	Clear land	Snow	over land	over water	over land	over water	Clear water	thickness	Water vapour

During Commissioning about 3100 products are acquired and processed



Commissioning Phase Activities – Geometric Calibration & Accuracy

Reference Image (Landsat 8 Pan, ~18 m CE90)

DESIS Image (after coarse rectification)

Accuracy w.r.t. Reference

19 scenes

#GCP: avarage 282 per scene #Control Points: avarage 1357 per scene

In case image matching works for a scene RMSE (east) = 20.1 ± 4.4 m RMSE (north) = 20.3 ± 2.9 m

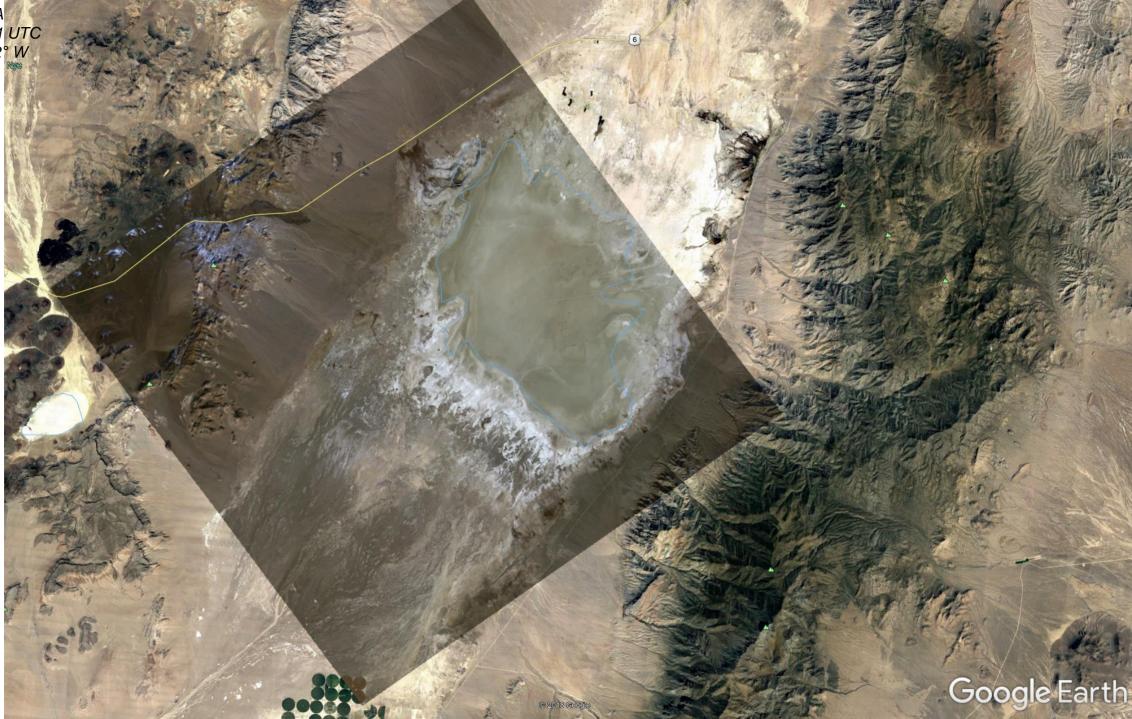
In case matching does not work and relying on boresight calibration RMSE ~400 m, but with peak values up to 1 km

Cascade of matching

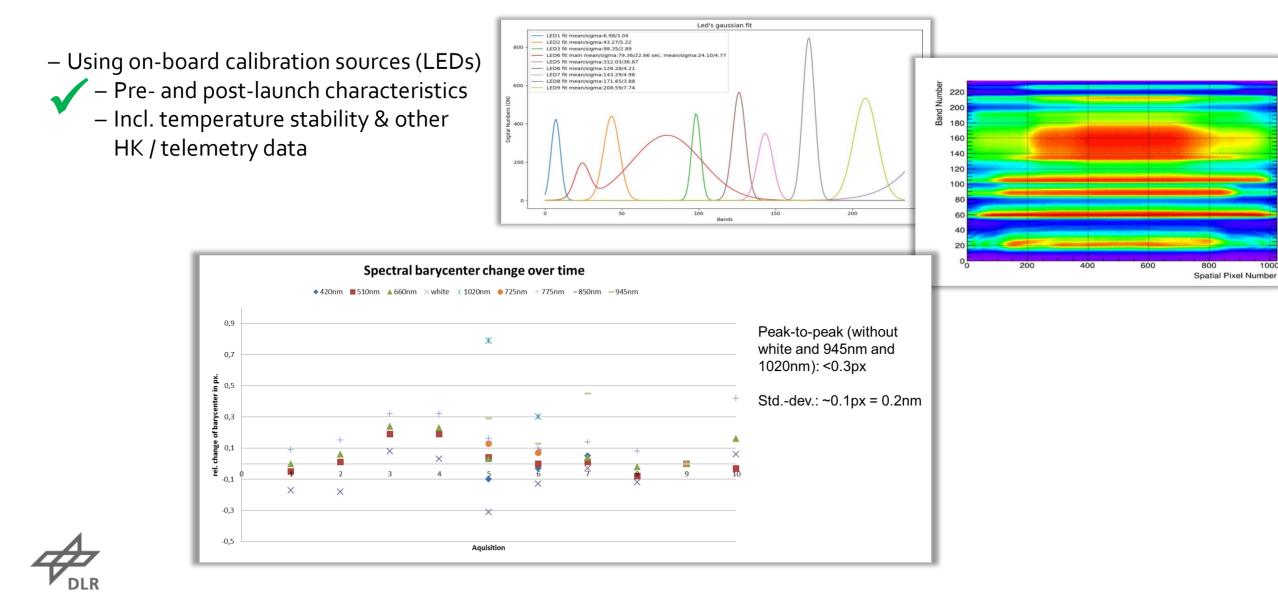


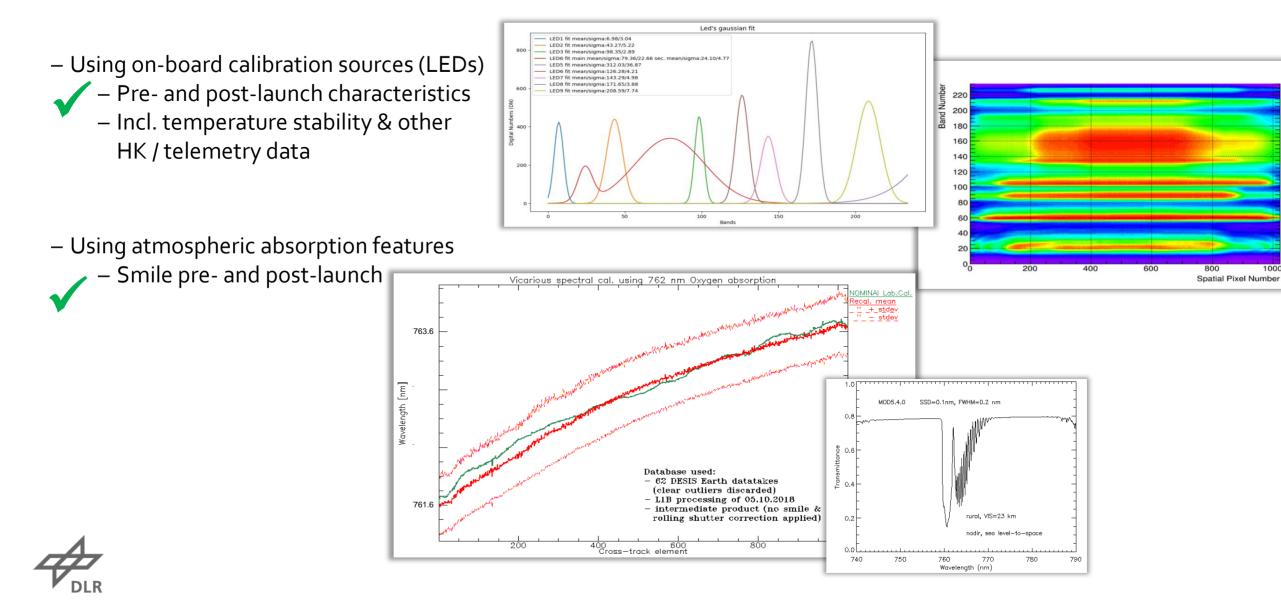
BRISK (Binary Robust Invariant Scalable Keypoints)
 Selected GCP to improveL包括(Socaneea的)
 Others are used for Quasity 本等を新知所知 ariant Feature Transform)

Railroad Valley, USA 13-12-2018 18:23:11 UTC 38.4467°N 115.7512° W Sun: 64.14°, 160.58° Incident Angle: 0.8° Railroad Valley, USA 13-12-2018 18:23:11 UTC 38.4467°N 115.7512° W

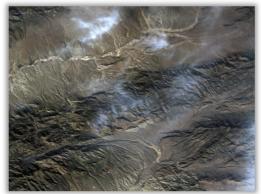




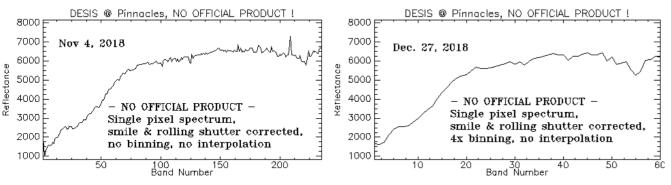


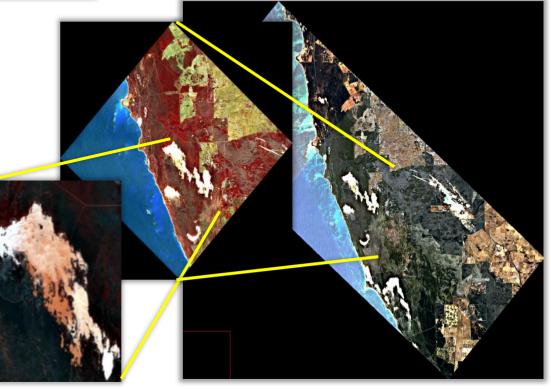


– Using CEOS RadCalNet sites, e.g. Railroad Valley

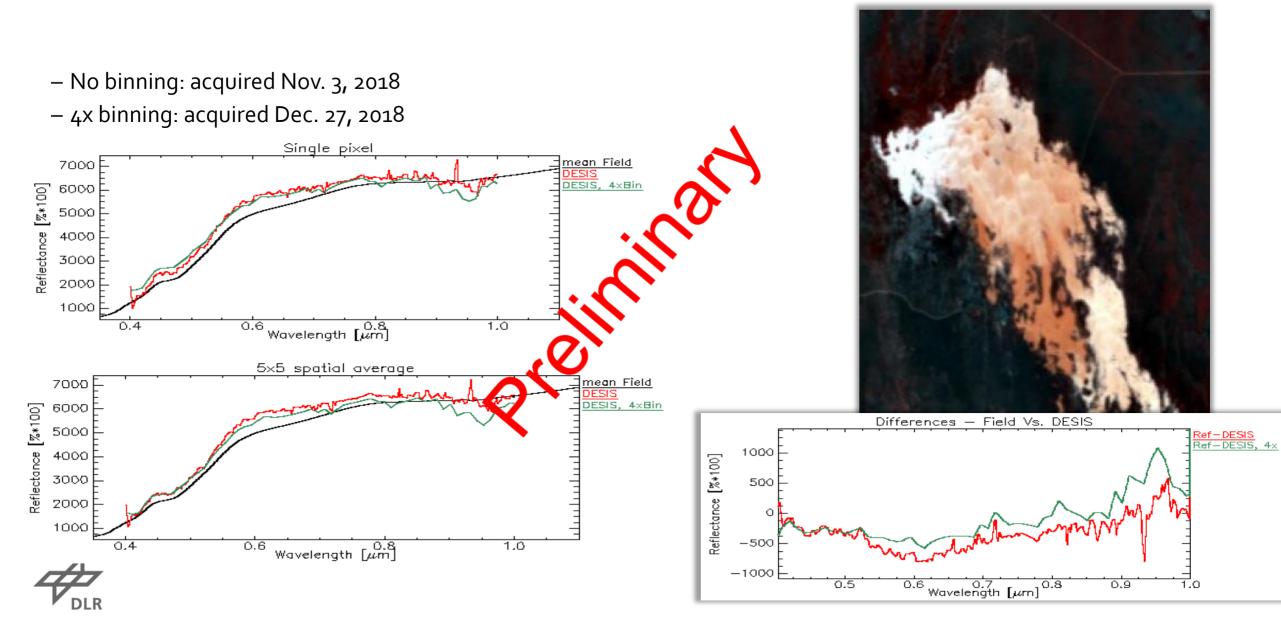


Using CEOS PICs sites & Pinnacles site (CSIRO) Different binning modes (2.55 nm, 10,2 nm)









금 0.35 0.30 <u>o</u> 0.25 a 0.20 0.15 0.10 RCN (ref) ₩ 0.05 DESIS (ref. RSP) [1000x1000 m] 0.00 L____ 400 500 600 700 800 900 1000 Wavelength (nm) 0.16 reflectance 0.14 0.12 0.10 0.08 0.08 BOA 0.06 ₩ 0.04 Abs. 0.00 L 500 600 700 800 900 1000 Wavelength (nm)

OUTPUT-L2A_290_tile02(RailroadValleyPlaya (2018-12-17))



Figure 1: The Railroad Valley Playa and the target for which the RadCalNet top-ofatmosphere reflectance spectra are representative (yellow).

DESIS scene

Time of acquisition: 13.12.2018, 18:21:18 UTC SZA = 64° Incidence = 0.8° (**nadir**) No BRDF correction

RadCalNET data

Time of acquisition: 17.12.2018, 18:30 UTC



Comparison Sentinel-2 DESIS

La Crau, France

04-02-2019 13:47:04 UTC

[; ^{0.30},

0.25 0.20 e 0.20 0.15

ja 0.10 0.05 g 0.00 L____ 400

8 0.07 0.06 g

BOA reflec 0.03 0.03

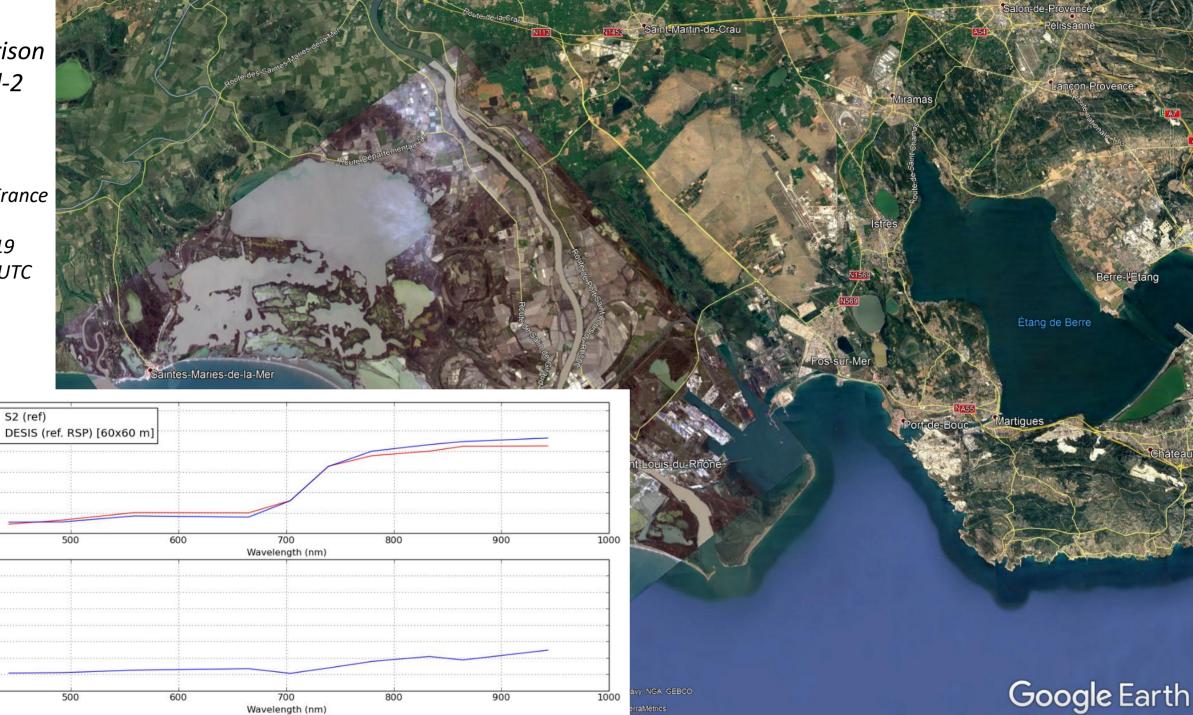
₩ 0.02 Abs. 0.00 ∟ 400

500

600

700

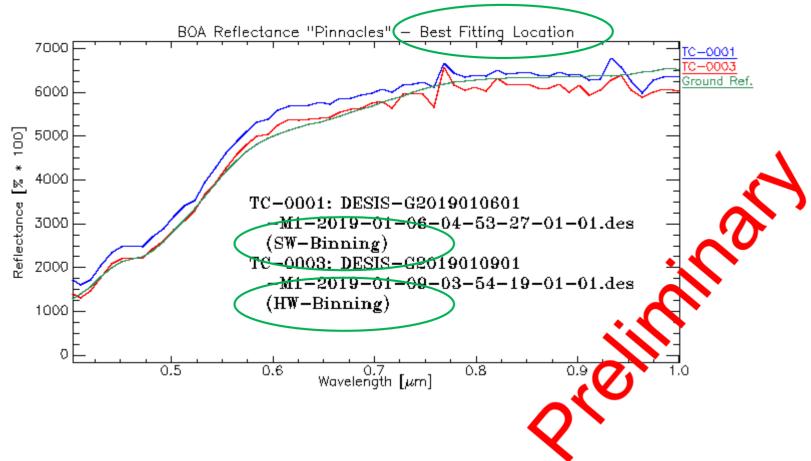
Wavelength (nm)



1000

900

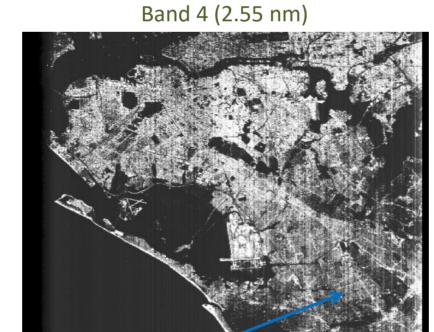
800





Striping - solvable

Band 1 (2.55 nm)



Band 22 (2.55 nm)





Most likely caused by PRNU coefficients, most noticeable in first ~30 bands (2.55 nm)

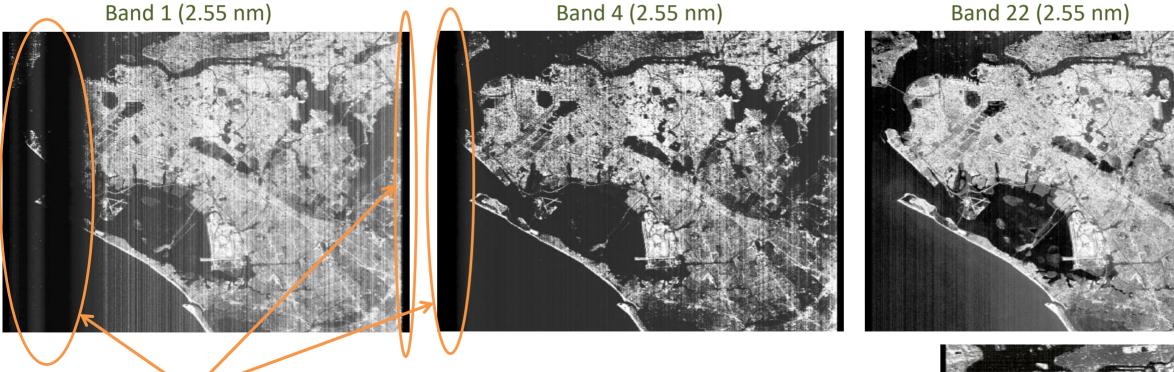
Striping

Band 100 (2.55 nm)



cross tr

Striping – not solvable



Manufacturing defects

Different Striping

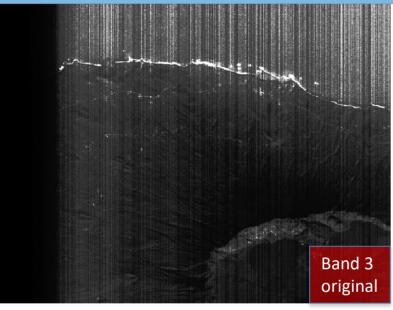


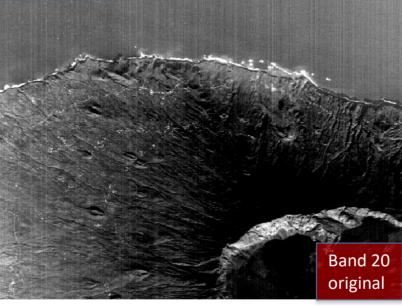
Most likely caused by Noise in DC, most noticeable in last ~30 bands (2.55 nm). Notice also horizontal striping of same magnitude. Cosmetics solution could be used, but not real solution Band 212 (2.55 nm)

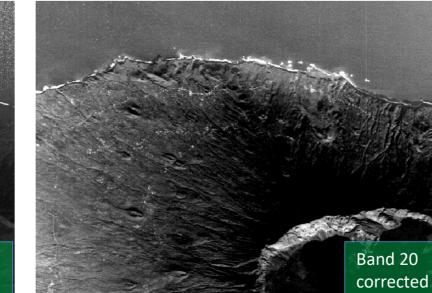


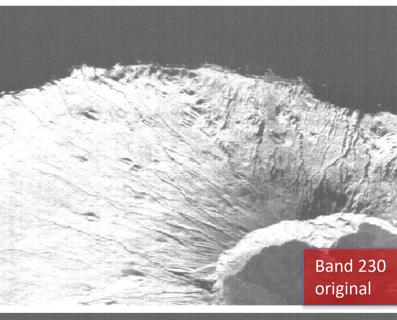
Comparison Original / Corrected

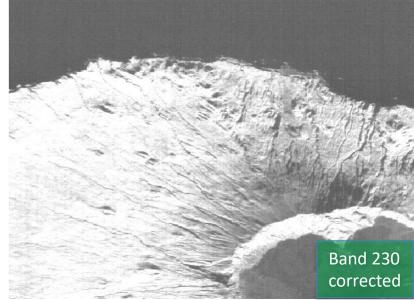
L1B radiance range stretched to highlight striping

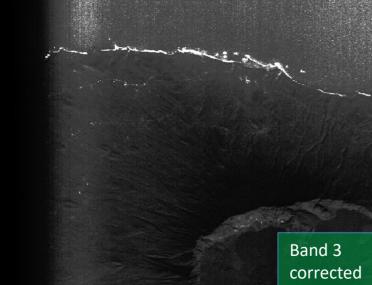












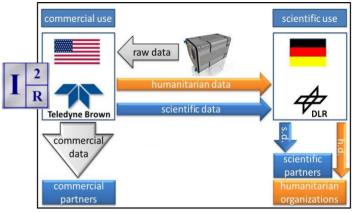
Data Policy

DESIS is to be operated by Teledyne (TBE):

- TBE will receive the raw data
- TBE has the exclusive right to license or transfer image data for commercial use.
- For scientific and humanitarian purposes, DLR has the right to:
 - Task DESIS, 2000 minutes/year
 - Request archived data

Distribution of 2.55 & 5.1 nm spectral sampled data is subject to NOAA approval

- For scientific purposes only:
 - DLR can share DESIS scientific data with other scientific organizations within projects; Data are free in this case for the partners
 - Scientific use includes:
 - basic and application oriented research,
 - projects by national and international educational or research institutions or by governmental institutions,
 - development and demonstration of future applications for scientific and/or operational use and
 - preparation and execution of government-funded education, research and development programs.



Summary and Conclusions and Outlook

- DESIS in-orbit functional tests successful
- Main findings during commissioning phase
 - Very few defective / unstable pixels (0.3%)
 - Temperature stability well within specification
 - Very high DC stability (~3%)
 - Processing chain up and running to L2A (rad. & geom. & atm.)
 - Including smile & rolling shutter correction
 - Geometric accuracy within 1 pixel (image-to-image matching)
 - Spectral characteristics consistent pre-/post- launch
 - Radiometric characterization ongoing
 - On-board calibration procedure ongoing

Outlook

- Cross-calibration with HISUI foreseen
- Multispectral instrument DECAM planned (fusion HSI and MS)

